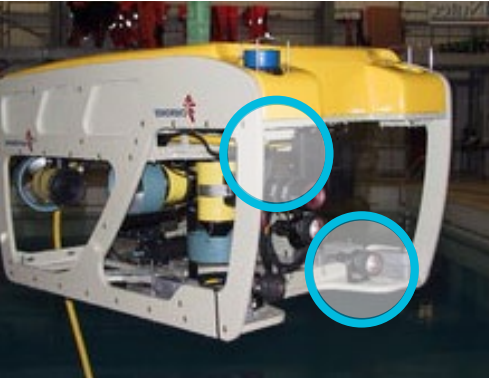
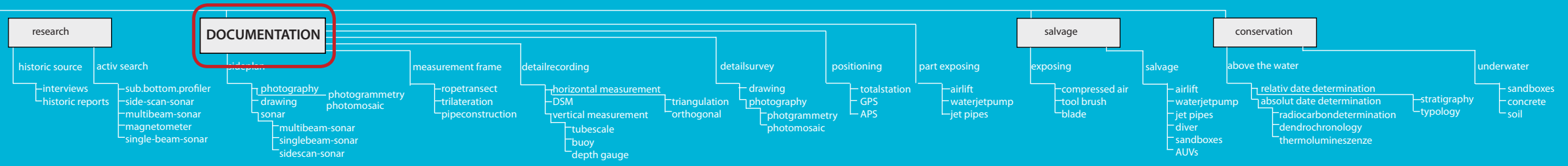


# USABILITY PROBLEMS workflow & product analysis



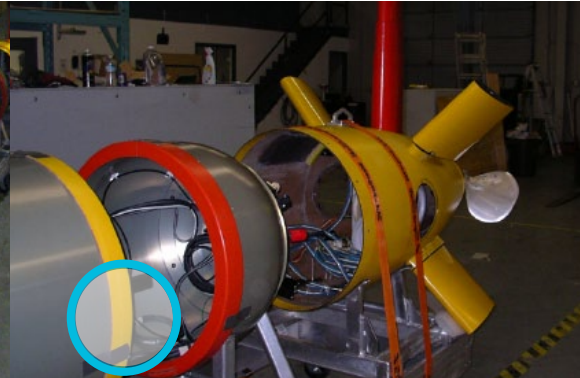
## ORIENTATION

The way to keep the AUV on track & on the right distance/depth is controlled by a variety of sensors



## SAFETY

The buoyancy-control is the key to salvage the vehicle in case of an total or partial breakdown



## RECORDING

Photo and video systems plus parts of the sensors used for orientation are installed for data gathering



## CONTROL

The control can be kept via sonic waves that allow limited data transfer and course correction